

**AMENDMENTS TO THE SPECIFICATION**

(1) Please replace the paragraph beginning "The signal processing circuit" on page 8 with the following amended paragraph:

The signal processing circuit 3x is placed to sample and hold an output voltage  $V_{sx}$  from the C-V conversion circuit 2x (i.e., the output of the operational amplifier 21) at intervals in synchronism with the square waves  $P1x$  and  $P2x$ . In this circuit 3x, signals resulting from the sample-and-hold processing ~~is then~~are then subjected to predetermined signal processing to output a detection signal  $OUTx$  that depends on an X-axis directional acceleration acting on the movable electrode 12 of the sensor element 10x. In order to have such operations, the signal processing circuit 3x is provided with two sample-and-hold circuits 4x and 5x, a differential amplifier circuit 6x, and a low-pass filter (LPF) 7x. The differential amplifier circuit 6x applies differential amplification to outputs from the two sample-and-hold circuits 4x and 5x.

(2) Please replace the paragraph beginning "In addition to the above" on page 10 with the following amended paragraph:

In addition to the above configurations, the acceleration detecting apparatus according to the present embodiment is provided with a control circuit 8. This control circuit 8 includes, as its essential component, a microcomputer 8A. Hence, based on a software-based operation of the microcomputer (CPU) 8A allows the control circuit 8 to provide the foregoing square waves  $P1x$ ,  $P2x$ ,  $P1y$  and  $P2y$  and the switch signals  $SRx$ ,  $S1x$ ,  $S2x$ ,  $SRy$ ,  $S1y$  and  $S2y$  at timings shown Fig. 2. The present embodiment employs a manner of switching on the corresponding switches when the switch signals  $SRx$ ,  $S1x$ ,  $S2x$ ,  $SRy$ ,  $S1y$  and  $S2y$  ~~becomes~~become high in level. The control circuit 8 may be produced, if necessary, by using digital logic circuits.